Axial Interface Unit

Various encoder interfaces and high-speed multi-axis control by analog commands for precise machine operation



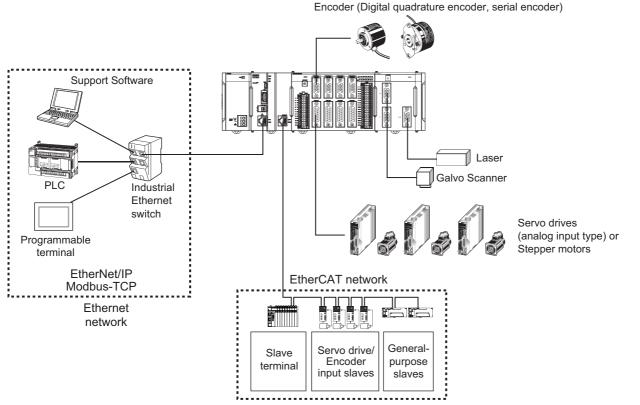
CK3W-AX

Features

- One CK3W-AX Unit controls up to four axes
- · Analog input servo drives or DirectPWM servo drives can be connected
- · Digital quadrature encoders, serial encoders, and sinusoidal encoders can be connected as encoder input
- 16 digital inputs and 16 digital outputs are built in

System Configurations

Basic System Configuration



*1. You will need this unit when you use the Galvo Scanner.

CK W Unit Configuration (CPU Rack/Expansion Rack)

The following shows the configuration of $CK \square W$ Units.

CPU Rack

The CK3W Unit configuration in the CPU Rack consists of a Power Supply Unit, CPU Unit, CK3W-AX Unit, CK3W-MD Unit, CK3W-AD Unit, CK3WECS Unit, CK3W-GC Unit, and End Cover.

Up to four CK3W Units (or up to two CK3W-AX Units) can be connected to the CPU Unit.

Expansion Rack

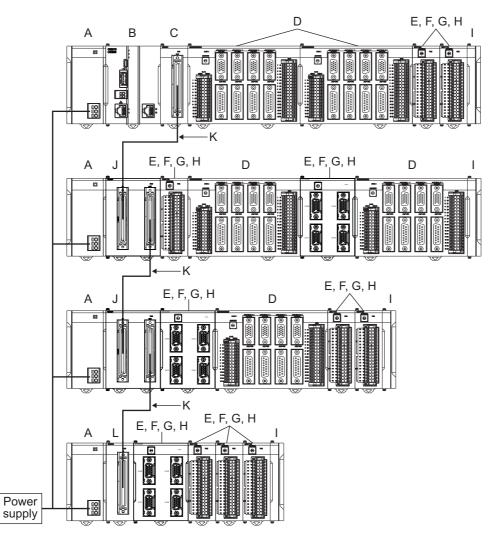
Up to one Expansion Rack can be added for the CK3M CPU Unit, and up to three Expansion Racks can be added for the CK5M CPU Unit. To connect an Expansion Rack, use the Expansion Master Unit (CK3W-EXM01) and Expansion Slave Unit (CK5W-EXS01, CK3W-EXS02). Up to four CK3W Units (or up to two CK3W-AX Units) can be installed to the Expansion Rack.

Connect the Expansion Master Unit (CK3W-EXM01) to the immediate right side of the CPU Unit. Connect the Expansion Slave Unit (CK5W-EXS01, CK3W-EXS02) to the immediate right side of the Power Supply Unit.

Unless the Expansion Master Unit (CK3W-EXM01) is connected adjacent to the right side of the CPU Unit, the Sys.Status register CK3WConfigErr becomes "5".

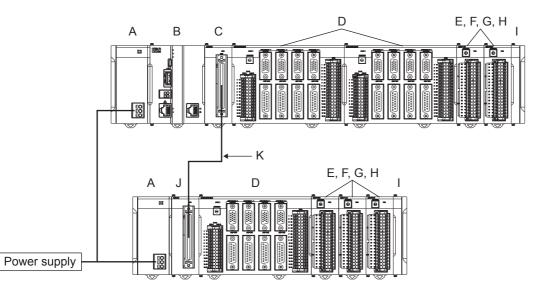
Use the CK3W-EXS02 for the Expansion Slave Unit farthest from the CPU Rack, and the CK5WEXS01 for the Expansion Slave Unit located in the middle. The CK5W-EXS01 can only be used with the CK5M CPU Unit. It can not be used with the CK3M CPU Unit.

For CK5M CPU Unit



Letter	Configuration	Remarks			
А	Power Supply Unit	Input the 24 V power source. Always wire the CPU Rack and Expansion Rack to the same power supply.			
В	CK5M-series CPU Unit	This is the Unit at the center of the motion control, which executes the motion program.			
С	CK3W-EXM01	Expansion Master Unit. Connect this Unit adjacent to the right side of the CPU Unit in the Expansion Rack.			
D	CK3W-AX Unit	Axis Interface Unit. For axis control, connect this to a Servo Drive and encoder.			
E	CK3W-MD Unit	Digital I/O Unit. You can add 16 digital inputs and 16 digital outputs.			
F	CK3W-AD Unit	Analog Input Unit. You can add 4 or 8 voltage inputs.			
G	CK3W-ECS Unit	Encoder Input Unit. You can connect four channels of the serial encoder.			
Н	CK3W-GC Unit	Laser Interface Unit. You can connect the Galvo Scanner compatible with the interface of XY2-100 or SL2-100.			
I	End Cover	Must be connected to the right end of the CPU Rack and Expansion Rack. The CPU Unit and the Expansion Slave Unit are each provided with one End Cover.			
J	CK5W-EXS01	Expansion Slave Unit. Use this in the Expansion Rack located in the middle. Connect this Unit to the immediate right side of the Power Supply Unit. This unit can only be used with the CK5M CPU Unit. It can not be used with the CK3M CPU Unit.			
к	Expansion cable	Use this cable to connect the Expansion Master Unit and Expansion Slave Unit. The cable length is 30 cm. Be sure to use the CK3W-CAX03A (30 cm) cable.			
L	CK3W-EXS02	Expansion Slave Unit. Use this for the Expansion Rack farthest from the CPU Rack. Connect this Unit to the immediate right side of the Power Supply Unit.			

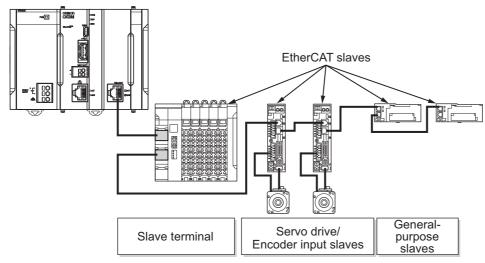
For CK3M CPU Unit



Letter	Configuration	Remarks			
А	Power Supply Unit	Input the 24 V power source. Always wire the CPU Rack and Expansion Rack to the same power supply.			
В	CK3M-series CPU Unit	This is the Unit at the center of the motion control, which executes the motion program.			
С	CK3W-EXM01	Expansion Master Unit. Connect this Unit adjacent to the right side of the CPU Unit in the Expansion Rack.			
D	CK3W-AX Unit	Axis Interface Unit. For axis control, connect this to a Servo Drive and encoder.			
E	CK3W-MD Unit	Digital I/O Unit. You can add 16 digital inputs and 16 digital outputs.			
F	CK3W-AD Unit	Analog Input Unit. You can add 4 or 8 voltage inputs.			
G	CK3W-ECS Unit	Encoder Input Unit. You can connect four channels of the serial encoder.			
Н	CK3W-GC Unit	Laser Interface Unit. You can connect the Galvo Scanner compatible with the interface of XY2-100 or SL2-100.			
I	End Cover	Must be connected to the right end of the CPU Rack and Expansion Rack. The CPU Unit and the Expansion Slave Unit are each provided with one End Cover.			
J	CK3W-EXS02	Expansion Slave Unit. Use this in the Expansion Rack. Connect this Unit adjacent to the right side of the Power Supply Unit.			
к	Expansion cable	Use this cable to connect the Expansion Master Unit and the Expansion Slave Unit. The cable length is 30 cm. Be sure to use the CK3W-CAX003A (30 cm) cable.			

EtherCAT Network Configuration

The EtherCAT network configuration consists of a Power Supply Unit, CPU Unit, End Cover, and EtherCAT slaves. Use the built-in EtherCAT port on the CK \square M-series CPU Unit to connect EtherCAT slaves.



EtherCAT is synchronized with the servo cycle of the CK \square M-series CPU Unit. This enables acquisition of the I/O data of slave terminals that are synchronized with the servo cycle.

Refer to the CK3M/CK5M-series Programmable Multi-Axis Controller User's Manual Hardware (Cat.No.0036) for information on using the NX-series EtherCAT Coupler Unit.

Ordering Information

Axial Interface Unit

The models and outline of specifications are given below.

Product name	Amplifier interface	Encoder interface	Output type	Model
	DirectPWM output			CK3W-AX1313N
	DA output (Filtered PWM)	Digital quadrature encoder/serial encoder		CK3W-AX1414N
	DA output (True DAC)		NPN type	CK3W-AX1515N
	DirectPWM output	Sinusoidal encoder/serial encoder		CK3W-AX2323N
xial Interface Unit	DirectPWM output			CK3W-AX1313P
	DA output (Filtered PWM)	Digital quadrature encoder/serial encoder		CK3W-AX1414P
	DA output (True DAC)		PNP type	CK3W-AX1515P
	DirectPWM output	Sinusoidal encoder/serial encoder	=	CK3W-AX2323P

Dedicated Cable for Wiring to Encoder Connector

Cable length	Model
3 m	CK3W-CAED03A
3 m	CK3W-CAEA03A
3 m	CK3W-CAES03A
3 m	CK3W-CAEW03A
3 m	CK3W-CAEAW03A
	3 m 3 m 3 m 3 m 3 m

Note: The encoder connection side has discrete wires. Wire in accordance with the encoder specifications.

Dedicated Cable for Wiring to Amplifier Connector

Туре	Cable length	Model
For FilteredPWM/TrueDAC type	3 m	CK3W-CAA03A
	0.9 m	CK3W-CAAD009A
For DirectPWM type	1.8 m	CK3W-CAAD018A
	3.6 m	CK3W-CAAD036A

Note: The amplifier connection side of the CK3W-CAA03A Cable has discrete wires. Wire in accordance with the servo drive specifications.

General Specifications

This section describes the Motion Controller specifications.

	Item	Specification	
Enclosure Grounding Method		Mounted in a panel	
		Ground to less than 100 Ω .	
	Ambient Operating Temperature	0 to 55°C	
	Ambient Operating Humidity	10% to 95% (with no condensation or icing)	
	Atmosphere	Must be free of corrosive gases.	
Operating Environment	Ambient Storage Temperature	-25 to 70°C (with no condensation or icing)	
	Vibration Resistance	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz, acceleration of 9.8 m/s ² 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)	
	Shock Resistance	Conforms to IEC 60068-2-27. 147 m/s ² , 3 times each in X, Y, and Z directions	
Insulation Resistance		20 M Ω min. between isolated circuits (at 100 VDC)	
Dielectric Strength		510 VAC between isolated circuits for 1 minute with a leakage current of 5 mA max.	
Applicable Standards		cULus, EU: EN 61326, RCM, KC, EAC *1	

***1.** The CK5M CPU Unit and CK5W-EXS01 are not EAC-compliant products.

Axis Interface Unit Specifications

The main specifications for axis interface are given below.

CK3W-AX1414□/-AX1515□

Item		Specification (CK3W-)				
It	em	AX1414N	AX1414P	AX1515N	AX1515P	
Address setting range		0 to F				
Number of channels	4 channels/Unit					
Encoder power supply output		5 VDC 500 mA/chan However, the total or	nel or less utput current of each U	nit is 1 A or less.		
	Input form	Line receiver input				
Digital quadrature encoder input	Maximum response frequency	Phases A, B, and C:	10 MHz			
Serial encoder input	Supported protocol	Contact your OMRO	N representative for inf	ormation on the support	protocols.	
Digital Hall sensor		4 points/channel (U,	V, W, T)			
OUTFlagB output		1 point/channel				
	Method	FilteredPWM type		TrueDAC type		
Analog output	Number of points	1 point/channel		2 points/channel		
Analog output	Output range	Between DACA+/DACB+ and DACA-/DACB-: -20 to 20 V Between DACA+/DACB+ and AGND: -10 to 10 V				
	Output form	Line driver output				
Pulse output	Output method	Pulse output + directional output, or phase difference output				
	Maximum output frequency	10 MHz				
Amp enable output		1 point/channel				
Fault input		1 point/channel				
	Digital input	4 points/channel (HOME, PLIM, NLIM, USER)				
Flags	Digital output	1 point/channel (EQU)				
	Number of points	16 inputs, 16 outputs				
General digital I/O	Internal common	NPN	PNP	NPN	PNP	
Power consumption		5 VDC: 4.5 W max. 5 VDC: 4.5 W max. 24 VDC: 10.8 W max. 24 VDC: 12.5 W max.				
Dimensions (height × depth × widt	h)	90(H)/80(D)/130(W)				
Weight		520 g max.				

CK3W-AX1313□/-AX2323□

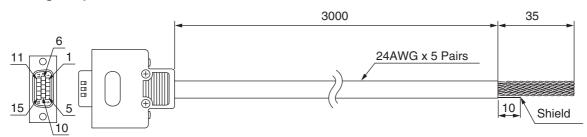
Ite	Specification (CK3W-)					
	AX1313N	AX1313P	AX2323N	AX2323P		
Address setting range		0 to F				
Number of channels		4 channels/Unit				
Encoder power supply output		5 VDC 500 mA/channel or less However, the total output current of each Unit is 1 A or less.				
Disitel suggesture encoder input	Input form	Line receiver input				
Digital quadrature encoder input	Maximum response frequency	Phases A, B, and C: 10 MHz				
Serial encoder input	Contact your OMRON	representative for info	rmation on the support p	rotocols.		

ltem		Specification (CK3W-)				
	item	AX1313N	AX1313P	AX2323N	AX2323P	
Oinvesidel encedeniment	Input signal			1-Vpp SIN/COS signal		
Sinusoidal encoder input	Maximum input frequency			2 MHz		
Digital Hall sensor	·	4 points/channel (U,	V, W, T)			
DirectPWM output		Amplifier interface un	ique to Delta Tau			
Amp enable output		1 point/channel (built into DirectPWM)				
Fault input		1 point/channel (built into DirectPWM)				
Flore	Digital input	4 points/channel (HOME, PLIM, NLIM, USER)				
Flags	Digital output	1 point/channel (EQU)				
Conoral digital I/O	Number of points	16 inputs, 16 outputs				
General digital I/O	Internal common	NPN	PNP	NPN	PNP	
Power consumption		5 VDC: 3.4 W max. 5 VDC: 3.0 W max. 24 VDC: 12.5 W max. 24 VDC: 13.1 W max.				
Dimensions (height × depth ×	width)	90(H)/80(D)/130(W)				
Weight		480 g max. 490 g max.				

Dedicated Cable for Wiring to Encoder Connector

The dedicated cables for wiring to the encoder connector are provided as an option. The encoder connection side has discrete wires. Wire in accordance with the encoder specifications.

For digital quadrature encoder CK3W-CAED03A



Туре	Pin No.	Cable color	Mark	Signal
Pair 1	11	Blue	Black	Encoder Power Supply (+5 VDC)
Pair I	13	Blue	Red	Encoder Power Supply (GND)
Pair 2	1, 5 * ¹	Pink	Black	Encoder A+ Serial Encoder DAT+
Pall 2	6, 10 *1	Pink	Red	Encoder A- Serial Encoder DAT-
Pair 3	2	Green	Black	Encoder B+
Pail 5	7	Green	Red	Encoder B-
Pair 4	3	Orange	Black	Encoder C+
Pail 4	8	Orange	Red	Encoder C-
Pair 5	15	Gray	Black	OutFlagB
Pail 5	14	Gray	Red	GND

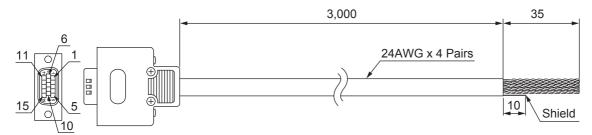
*1. In order to make a connection with the OMRON G5-series Servo Drive R88D-KT ., Pin 1 and Pin 5, and Pin 6 and Pin 10 are short-circuited inside the connector.

You can also connect a normal digital quadrature encoder which does not use serial encoder DAT by disabling the serial encoder.

Note: The cable shield is connected to the connector shell of the encoder connector.

When using this cable, set to OutFlagD = 1, and disable the serial encoder DAT terminating resistance.

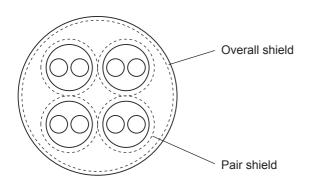
For Sinusoidal Encoder



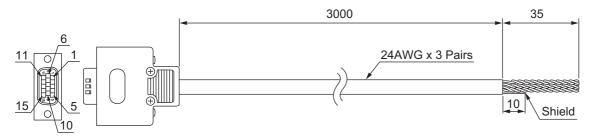
Туре	Pin No.	Cable color	Signal
Pair 1	11	Black	Encoder Power Supply (+5 VDC)
Fall I	13	Blue	Encoder Power Supply (GND)
Pair 2	1	Black	SIN+
Pall 2	6	Red	SIN-
Dein 0	2	Black	COS+
Pair 3	7	White	COS-
Doir 4	3	Black	INDEX+
Pair 4	8	Green	INDEX-

Note: The cable shield consists of an overall shield and pair shields.

The overall shield is connected to the connector shell of the encoder connector. The pair shields are connected to the Encoder Power Supply (GND) pin.



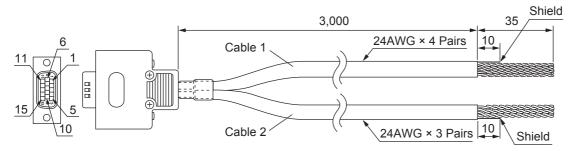
For Serial Encoder



Туре	Pin No.	Cable color	Mark	Signal
Pair 1	12	Blue	Black	Encoder Power Supply (+5 VDC)
	14	Blue	Red	Encoder Power Supply (GND)
Pair 2	4	Pink	Black	Encoder CLK+
	9	Pink	Red	Encoder CLK-
Doir 2	5	Green	Black	Serial Encoder DAT+
Pair 3	10	Green	Red	Serial Encoder DAT-

Note: The cable shield is connected to the connector shell of the encoder connector.

For "Digital Quadrature Encoder + UVW Signal" or "Digital Quadrature Encoder + Serial Encoder"



Cable 1

Туре	Pin No.	Cable color	Mark	Signal
Pair 1	11	Blue	Black	Encoder Power Supply (+5 VDC)
Fall I	13	Blue	Red	Encoder Power Supply (GND)
Pair 2	1	Pink	Black	Encoder A+
Fall 2	6	Pink	Red	Encoder A-
Dein 0	2	Green	Black	Encoder B+
Pair 3	7	Green	Red	Encoder B-
Pair 4	3	Orange	Black	Encoder C+
rdli 4	8	Orange	Red	Encoder C-

Note: The cable shield is connected to the connector shell of the encoder connector.

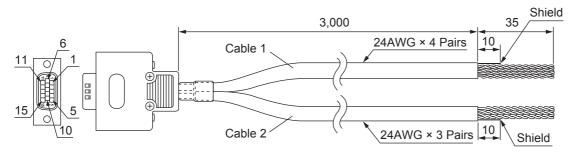
Cable 2

Turne	Pin No.	Cable color	Mark	Signal	
Туре				U, V, W	Serial Encoder
Pair 1	12	Blue	Black	Encoder Power Supply (+5 VDC)	
Pall I	14	Blue	Red	Encoder Power Supply (GND)	
Pair 2	4	Pink	Black	Hall sensor U	Serial Encoder CLK+
Pair 2	9	Pink	Red	Hall sensor V	Serial Encoder CLK-

Туре	Pin No.	Cable color	Mark	Signal	
				U, V, W	Serial Encoder
Pair 3	5	Green	Black	Hall sensor W	Serial Encoder DAT+
	10	Green	Red	Hall sensor T	Serial Encoder DAT-

Note: The cable shield is connected to the connector shell of the encoder connector.

For "Sinusoidal Encoder + UVW Signal" or "Sinusoidal Encoder + Serial Encoder"

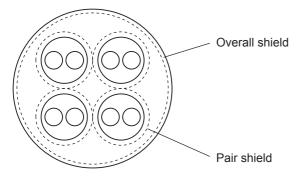


Cable 1

Туре	Pin No.	Cable color	Signal
Pair 1	11	Black	Encoder Power Supply (+5 VDC)
Fall I	13	Blue	Encoder Power Supply (GND)
Pair 2	1	Black	SIN+
Fall 2	6	Red	SIN-
D. i. o	2	Black	COS+
Pair 3	7	White	COS-
Pair 4	3	Black	INDEX+
	8	Green	INDEX-

Note: The cable shield consists of an overall shield and pair shields.

The overall shield is connected to the connector shell of the encoder connector. The pair shields are connected to the Encoder Power Supply (GND) pin.



Cable 2

Туре	Pin No.	Cable color	Signal	
туре			U, V, W	Serial Encoder
Pair 1	12	Blue	Encoder Power Supply (+5 VDC)	
Pair I	14	White	Encoder Power Supply (GND)	
Pair 2	4	Black	Hall sensor U	Serial Encoder CLK+
Pail 2	9	Green	Hall sensor V	Serial Encoder CLK-
Pair 3	5	Yellow	Hall sensor W	Serial Encoder DAT+
	10	Brown	Hall sensor T	Serial Encoder DAT-

Note: The cable shield is connected to the connector shell of the encoder connector.

Dedicated Cable for Wiring to Amplifier Connector

For FilteredPWM/TrueDAC type

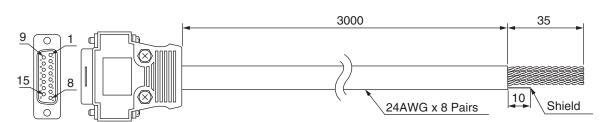
This section describes the cable used for the CK3W-AX1414□/-AX1515□ Units.

The dedicated cable for wiring to the FilteredPWM/TrueDAC type amplifier connector is provided as an option.

The amplifier connection side has discrete wires. Wire in accordance with the Servo Drive specifications.

The cable model is as shown below.

Туре	Model	Length
For FilteredPWM/TrueDAC type	CK3W-CAA03A	3 m



Туре	Pin No.	Cable color	Mark	Signal
Dein 4	1	Blue	Black 1 dot	Analog output A+
Pair 1	9	Blue	Red 1 dot	Analog output A-
Pair 2	2	Pink	Black 1 dot	Analog output B+
Pair 2	10	Pink	Red 1 dot	Analog output B-
Dein 2	3	Green	Black 1 dot	Analog GND
Pair 3	3	Green	Red 1 dot	Analog GND
Dein 4	5	Orange	Black 1 dot	Pulse output +
Pair 4	12	Orange	Red 1 dot	Pulse output -
Dein C	6	Gray	Black 1 dot	Directional output +
Pair 5	13	Gray	Red 1 dot	Directional output -
Dein C	4	Blue	Black 2 dot	Fault input +
Pair 6	11	Blue	Red 2 dot	Fault input -
Dein 7	7	Pink	Black 2 dot	Amp enable NO
Pair 7	15	Pink	Red 2 dot	Amp enable common
Doir 9	8	Green	Black 2 dot	Amp enable NC
Pair 8	15	Green	Red 2 dot	Amp enable common

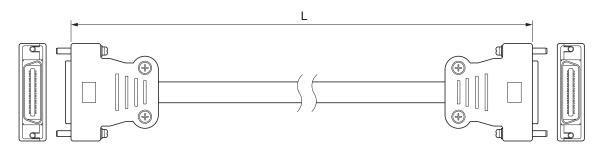
Note: The cable shield is connected to the connector shell of the amplifier connector.

For DirectPWM type

This section describes cables used for the CK3W-AX1313□/-AX2323□ Units.

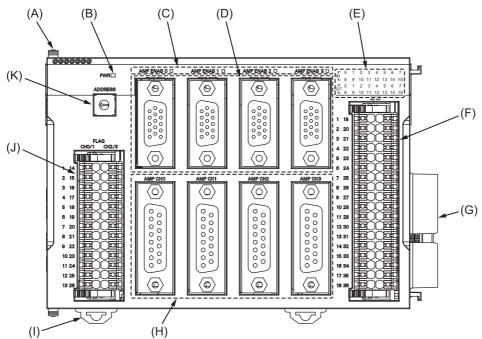
Be sure to use the following cables for the DirectPWM type amplifier connector.

Туре	Model	Length
	CK3W-CAAD009A	0.9 m
For DirectPWM type	CK3W-CAAD018A	1.8 m
	CK3W-CAAD036A	3.6 m



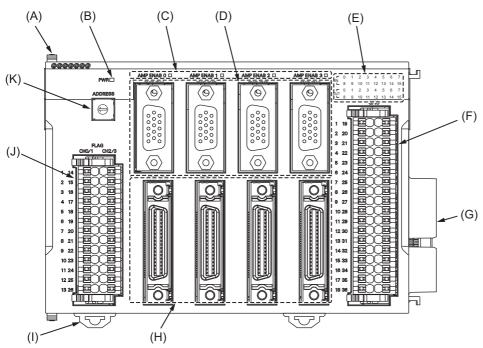
Part Names and Functions

CK3W-AX1414□/-AX1515□



Letter	Name	Function	
А	Slider	Holds the Units together.	
В	Power supply status indicator Shows the power supply status.		
С	Amp enable status indicator	Shows the Amp enable status.	
D	Encoder connector	Connects the encoder.	
Е	General digital input/output status indicator Shows the general digital input/output status.		
F	General digital I/O connection terminal block Connects the general digital input/output.		
G	Unit connector	Connector that connects to the Unit.	
Н	Amplifier connector Connects the amplifier.		
I	DIN Track mounting hook Used to mount the Unit to a DIN Track.		
J	Flag connection terminal block	Connects the HOME/PLIM/NLIM/USER inputs and EQU output.	
К	Address switch	Sets the Gate3 Index.	

CK3W-AX1313□/-AX2323□



Axial Interface Unit CK3W-AX

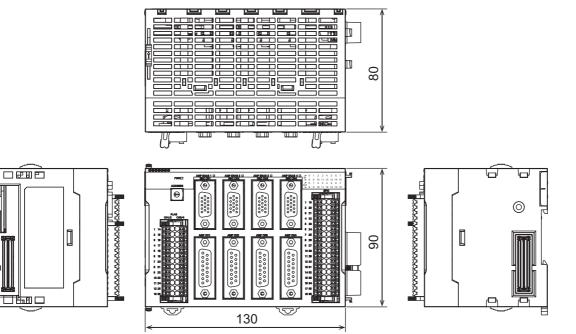
Letter	Name	Function	
А	Slider	Holds the Units together.	
В	Power supply status indicator Shows the power supply status.		
С	Amp enable status indicator	Shows the Amp enable status.	
D	Encoder connector Connects the encoder.		
Е	General digital input/output status indicator	Shows the general digital input/output status.	
F	General digital I/O connection terminal block	erminal block Connects the general digital input/output.	
G	Unit connector Connector that connects to the Unit.		
Н	Amplifier connector	Connects the amplifier.	
I	DIN Track mounting hook Used to mount the Unit to a DIN Track.		
J	Flag connection terminal block	Connects the HOME/PLIM/NLIM/USER inputs and EQU output.	
К	Address switch	Sets the Gate3 Index.	

Axial Interface Unit CK3W-AX

Dimensions

Axis Interface Unit

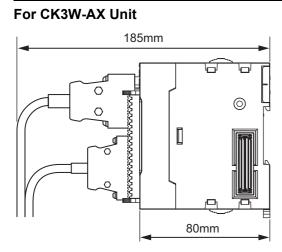
(Unit: mm)



Axis Interface Unit

Model	Unit width (mm)
CK3W-AX1313N	
CK3W-AX1414N	—
CK3W-AX1515N	_
CK3W-AX2323N	120
CK3W-AX1313P	- 130
CK3W-AX1414P	
CK3W-AX1515P	—
CK3W-AX2323P	

Installation Height



Related Manuals

The following manuals are related. Use these manuals for reference. Contact your OMRON representative for information on how to procure these manuals.

Manual name	Cat. No.	Application	Description
CK3M/CK5M-series Programmable Multi- Axis Controller Hardware User's Manual	O036	Learning the basic specifications of the CK3M/CK5M-series Pro- grammable Multi-Axis Controller, including introductory information, design, installation, and mainte- nance. Mainly hardware information is provided.	An introduction to the entire CK3M/CK5M-series system is pro- vided along with the following information. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection
Power PMAC User's Manual	O014	Learning the features and usage examples of the Motion Control- ler.	The following information is provided on the Motion Controller. Basic functions Setup examples Programming examples
Power PMAC Software Reference Manual	O015	Learning how to program Motion Controller.	The following information is provided on the Motion Controller. • Details of commands • Details of data structure
Power PMAC IDE User Manual	O016	Learning how to operate Power PMAC IDE, the integrated devel- opment environment of the Con- troller.	Describes the operating procedures of Power PMAC IDE, and examples of how to start the system.
Power PMAC-NC Quick Start Manual	O017	Briefly understanding the basic usage of Power PMAC-NC.	Describes the Quick setup procedure to run Power PMAC-NC on a desktop PC by showing some examples.
Power PMAC-NC .ini Configuration Manual	O018	Configuring an application for CNC devices by using Power PMAC-NC.	Describes how to set up <i>PowerPmacNC.ini</i> , the setup data file to be loaded when Power PMAC-NC starts.
Power PMAC-NC Software User Manual	O019	Learning about usage and fea- tures of Power PMAC-NC, Sup- port Software required to use the Controller for CNC devices.	The following information is provided on Power PMAC-NC. • How to use the software • Features included in the software • Features that can be customized
Power PMAC-NC Mill G-Code Manual	O020	Creating programs for CNC devices by using Power PMAC-NC.	Describes the basic G-code set that can be used for Power PMAC-NC, and relevant instructions.

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PMAC is an abbreviation for Programmable Multi Axis Controller.

Terms and Conditions Agreement

Read and understand this catalog.

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

Warranties.

(a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied.

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