

Data sheet for SINAMICS G120C

Article No.: 6SL3210-1KE22-6UF1

Client order no. : Order no. : Offer no. : Remarks :





Figure similar

	Rated data			
In	Input			
	Number of phases	3 AC		
	Line voltage	380 480 V +10 %	% -20 %	
	Line frequency	47 63 Hz		
	Rated current (LO)	33.00 A		
	Rated current (HO)	24.10 A		
Output				
	Number of phases	3 AC		
	Rated voltage	400V IEC	480V NEC 1)	
	Rated power (LO)	11.00 kW	15.00 hp	
	Rated power (HO)	7.50 kW	10.00 hp	
	Rated current (LO)	25.00 A		
	Rated current (HO)	16.50 A		
	Rated current (IN)	26.00 A		
	Max. output current	33.00 A		
	Pulse frequency	4 kHz		
	Output frequency for vector control	0 240 Hz		
	Output frequency for V/f control	0 550 Hz		

Overload capability

Low Overload (LO)

 $150\,\%$ base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

Communication

200~% base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos\phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	66 dB	
Power loss	292.0 W	
Filter class (integrated)	Unfiltered	
Communication		

PROFINET.	EtherNet/IP

Inputs / outputs		
Standard digital inputs		
Number	6	
Switching level: 0→1	11 V	
Switching level: 1→0	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number	1	
Digital outputs		
Number as relay changeover contact	1	
Output (resistive load)	DC 30 V, 0.5 A	
Number as transistor	1	
Output (resistive load)	DC 30 V, 0.5 A	
Analog / digital inputs		
Number	1 (Differential input)	
Resolution	10 bit	
Switching threshold as digital input		
0→1	4 V	
1→0	1.6 V	
Analog outputs		
Number	1 (Non-isolated output)	
PTC/ KTY interface		

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5\,^{\circ}\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Amb	ient conditions	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.018 m ³ /s (0.636 ft ³ /s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Connections		
Signal cable		
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)	
Line side		

V/6	rcin	ın

Version	Plug-in screw terminals
Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)

Motor end

Version	Plug-in screw terminals
Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)

DC link (for braking resistor)

Version	Plug-in screw terminals
Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw

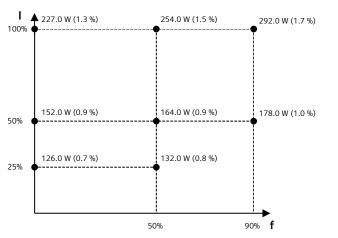
Max. motor cable length

Shielded	150 m (492.13 ft)
Unshielded	150 m (492.13 ft)

Mechanical data		
IP20 / UL open type		
FSC		
4.40 kg (9.70 lb)		
140 mm (5.51 in)		
295 mm (11.61 in)		
208 mm (8.19 in)		

Standards		
Compliance with standards	UL, cUL, CE, C-Tick (RCM)	

Converter losses to IEC61800-9-2*		
Efficiency class	IE2	
Comparison with the reference converter (90% / 100%)	32.5 %	



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

^{*}converted values

 $^{^{1)}}$ The output current and HP ratings are valid for the voltage range 440V-480V